

5/12-23

Q1

a)

P	R	Q	$P \Rightarrow R$	$(P \Rightarrow R) \Leftrightarrow Q$
T	T	T	T	T
T	T	F	T	F
T	F	T	F	F
T	F	F	F	T
F	T	T	T	T
F	T	F	T	F
F	F	T	T	T
F	F	F	T	F

b) continuing the truth table for $R \Rightarrow P$ gives:

...

$R \Rightarrow P$	$(R \Rightarrow P) \Leftrightarrow Q$
T	T
T	F
T	T
T	F
F	F
F	T
T	T
T	F

we see that $(R \Rightarrow P) \Leftrightarrow Q$ and $(P \Rightarrow R) \Leftrightarrow Q$ are NOT logically equivalent since they have different truth table

Q2

a) $e^{i\pi/2} \cdot (2+i) = (\cos(\frac{\pi}{2}) + i \sin(\frac{\pi}{2})) (2+i)$
 using Euler's formula
 $= i(2+i) = \underline{\underline{-1 + 2i}}$

b) $(\frac{\sqrt{2}}{2} + i \frac{\sqrt{2}}{2})^4 = (\cos(\frac{\pi}{4}) + i \sin(\frac{\pi}{4}))^4$
 $= (e^{i\frac{\pi}{4}})^4 = e^{4i\frac{\pi}{4}} = e^{i\pi} = \cos(\pi) + i \sin(\pi) = \underline{\underline{-1}}$

Q3

Given for all $n \in \mathbb{Z}_{\geq 2}$:

$$S_n = \sum_{k=2}^n \frac{k}{2}$$

$$a) S_2 = \sum_{k=2}^2 \frac{k}{2} = \frac{2}{2} = 1$$

$$S_3 = \sum_{k=2}^3 \frac{k}{2} = \frac{2}{2} + \frac{3}{2} = \frac{5}{2}$$

$$S_4 = \sum_{k=2}^4 \frac{k}{2} = \frac{2}{2} + \frac{3}{2} + \frac{4}{2} = \frac{9}{2}$$

$$b) \text{ Claim: } S_n = \frac{n^2 + n - 2}{4} \text{ for all } n \in \mathbb{Z}_{\geq 2}.$$

showing using induction on n :

Base case: For $n=2$ we have:

$$S_2 = \frac{2^2 + 2 - 2}{4} = \frac{4}{4} = 1, \text{ so the expression is true for } n=2.$$

Induction step:

Assuming true for $n-1$ for $n \in \mathbb{Z}_{\geq 2}$, so:

$$S_{n-1} = \frac{(n-1)^2 + (n-1) - 2}{4}$$

$$\text{Rewriting: } S_n = \sum_{k=2}^n \frac{k}{2} = \sum_{k=2}^{n-1} \frac{k}{2} + \frac{n}{2} = S_{n-1} + \frac{n}{2}$$

$$= \frac{(n-1)^2 + (n-1) - 2}{4} + \frac{n}{2}$$

$$= \frac{n^2 + \cancel{1} - 2n + n - \cancel{1} - 2}{4} + \frac{2n}{4}$$

$$= \frac{n^2 + n - 2}{4}$$

We here see that if the expression is true for $n-1$, it is also true for n , for any $n \in \mathbb{Z}_{\geq 2}$.

Along with the base step, we thus have that the expression is true for all $n \in \mathbb{Z}_{\geq 2}$

(2)

Q4 Given $\underline{\underline{A}} = \begin{bmatrix} 1 & -2 \\ -3 & 7 \end{bmatrix}$

a) $\underline{\underline{A}}$ is invertible if $\det(\underline{\underline{A}}) \neq 0$.

$$\det(\underline{\underline{A}}) = 1 \cdot 7 - (-3) \cdot (-2) = 7 - 6 = 1 \neq 0, \text{ so } \underline{\underline{A}} \text{ is invertible.}$$

Finding the inverse:

$$[\underline{\underline{A}} \mid \underline{\underline{I}}_2] = \left[\begin{array}{cc|cc} 1 & -2 & 1 & 0 \\ -3 & 7 & 0 & 1 \end{array} \right] \xrightarrow{R_2: R_2 + 3 \cdot R_1} \left[\begin{array}{cc|cc} 1 & -2 & 1 & 0 \\ 0 & 1 & 3 & 1 \end{array} \right]$$

$$\xrightarrow{R_1: R_1 + 2 \cdot R_2} \left[\begin{array}{cc|cc} 1 & 0 & 7 & 2 \\ 0 & 1 & 3 & 1 \end{array} \right], \text{ so } \underline{\underline{A}}^{-1} = \begin{bmatrix} 7 & 2 \\ 3 & 1 \end{bmatrix}$$

b) $\underline{\underline{B}} \in \mathbb{R}^{n \times n}$ is an invertible square matrix for an $n \in \mathbb{N}$.

Assuming $\lambda = 0$ is an eigenvalue of $\underline{\underline{B}}$, then a corresponding eigenvector $\underline{\underline{v}}$ must exist such that

$$\underline{\underline{B}} \cdot \underline{\underline{v}} = 0 \cdot \underline{\underline{v}} = \underline{\underline{0}}, \text{ where } \underline{\underline{v}} \neq \underline{\underline{0}}.$$

Since an eigenvector is a proper (non-zero) vector, then not only the zero-vector is a solution, and thus $\underline{\underline{B}}$ does not have full rank, so $\rho(\underline{\underline{B}}) \neq 2$. According to Corollary 7.25 a matrix is invertible if and only if it has full rank, $\rho(\underline{\underline{B}}) = 2$. Hence, we conclude that $\underline{\underline{B}}$ does not have an eigenvalue of 0.

Alternatively: Since $\underline{\underline{B}}$ is invertible, then $\underline{\underline{B}}^{-1}$ exists, and then

$$\underline{\underline{B}} \underline{\underline{v}} = \underline{\underline{0}} \Leftrightarrow \underline{\underline{B}}^{-1} \underline{\underline{B}} \underline{\underline{v}} = \underline{\underline{B}}^{-1} \underline{\underline{0}} \Leftrightarrow \underline{\underline{v}} = \underline{\underline{0}}$$

③ This is a contradiction since $\underline{\underline{v}}$ must be non-zero. Hence, 0 is not an eigenvalue of $\underline{\underline{B}}$.

Q5

V is the subspace in $\mathbb{R}(z)$ consisting of polynomials of up to degree 2.

An ordered basis γ is chosen for V :

$$\gamma = (1 + 2z, 2 + z - z^2, z^2)$$

A linear map $L: V \rightarrow V$ is given by:

$${}_{\gamma}[L]_{\gamma} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

According to Theorem 10.31
a) The mapping matrix consists of the images of the γ -basis vectors as columns. We thus see from the first two columns, that the first and second γ -basis vectors, $1 + 2z$ and $2 + z - z^2$, map to the 0-polynomial and hence belong to the kernel of L , $\ker(L)$. The third γ -basis vector, z^2 , does not.

For the polynomial $1 + 2z + z^2$, which has the γ -coordinate vector: $[1 + 2z + z^2]_{\gamma} = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$, we see:

$${}_{\gamma}[L]_{\gamma} \cdot [1 + 2z + z^2]_{\gamma} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \neq \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}.$$

So, it does not belong to the kernel of L .

b) We have $\dim(V) = 3$. According to the rank-nullity theorem, $\dim(V) = \dim(\ker(L)) + \dim(\text{image}(L))$.

Since the first two γ -basis vectors, which are linearly independent, belong to $\ker(L)$, then $\dim(\ker(L))$ is at least 2. Since we from a) have a polynomial with a non-zero image, then $\dim(\text{image}(L))$ is at least 1.

We conclude that $\dim(\ker(L)) = 2$ and $\dim(\text{image}(L)) = 1$

so that the rank-nullity theorem is fulfilled.

(4)

A basis for the kernel must thus consist of two polynomials, which can be:

$$(1 + 2z, 2 + z - z^2)$$

A basis for the image space consists of one polynomial, which can be:

$$(2 + z - z^2)$$

Q 6 Given real system of differential equations:

$$\begin{bmatrix} f_1'(t) \\ f_2'(t) \end{bmatrix} = \underbrace{\begin{bmatrix} 2 & 1 \\ 5 & -2 \end{bmatrix}}_{\underline{A}} \begin{bmatrix} f_1(t) \\ f_2(t) \end{bmatrix}$$

a) TLZ

We can identify a coefficient matrix \underline{A} but no forcing functions, so $\underline{q}(t) = \begin{bmatrix} q_1(t) \\ q_2(t) \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$. According to Definition 12.10 the system is homogeneous.

b) Eigenvalues found by solving the characteristic equation:

$$\det(\underline{A} - \lambda \cdot \underline{I}_2) = \det\left(\begin{bmatrix} 2-\lambda & 1 \\ 5 & -2-\lambda \end{bmatrix}\right) = (2-\lambda)(-2-\lambda) - 5 \cdot 1$$

$$= \lambda^2 - 4 - 5 = \lambda^2 - 9 = 0 \quad \Leftrightarrow \quad \lambda^2 = 9 \quad \Leftrightarrow \quad \lambda = \begin{Bmatrix} 3 \\ -3 \end{Bmatrix}$$

Corresponding eigenvectors:

For $\lambda = 3$: $\begin{bmatrix} 2-3 & 1 & | & 0 \\ 5 & -2-3 & | & 0 \end{bmatrix} = \begin{bmatrix} -1 & 1 & | & 0 \\ 5 & -5 & | & 0 \end{bmatrix} \xrightarrow{R_2: R_2 + 5R_1} \begin{bmatrix} -1 & 1 & | & 0 \\ 0 & 0 & | & 0 \end{bmatrix}$

$\xrightarrow{R_1: (-1) \cdot R_1} \begin{bmatrix} 1 & -1 & | & 0 \\ 0 & 0 & | & 0 \end{bmatrix} \Leftrightarrow v_1 = v_2 \Leftrightarrow \underline{v} = \begin{bmatrix} 1 \\ 1 \end{bmatrix} t, t \in \mathbb{R}$
 where $gm(3) = 1$

For $\lambda = -3$: $\begin{bmatrix} 2+3 & 1 & | & 0 \\ 5 & -2+3 & | & 0 \end{bmatrix} = \begin{bmatrix} 5 & 1 & | & 0 \\ 5 & 1 & | & 0 \end{bmatrix} \xrightarrow{R_2: R_2 - R_1} \begin{bmatrix} 5 & 1 & | & 0 \\ 0 & 0 & | & 0 \end{bmatrix}$

$\xrightarrow{R_1: \frac{1}{5} \cdot R_1} \begin{bmatrix} 1 & \frac{1}{5} & | & 0 \\ 0 & 0 & | & 0 \end{bmatrix} \Leftrightarrow v_1 = -\frac{1}{5} v_2 \Leftrightarrow \underline{v} = \begin{bmatrix} -\frac{1}{5} \\ 1 \end{bmatrix} t, t \in \mathbb{R}$
 where $gm(-3) = 1$

Since $gm(3) = am(3) = 1$ and $gm(-3) = am(-3) = 1$, then an eigenbasis exists, and according to Theorem 12.16 the

⑤ general real solution is: $\begin{bmatrix} f_1(t) \\ f_2(t) \end{bmatrix} = c_1 e^{3t} \begin{bmatrix} 1 \\ 1 \end{bmatrix} + c_2 e^{-3t} \begin{bmatrix} -\frac{1}{5} \\ 1 \end{bmatrix}, c_1, c_2 \in \mathbb{R}$.